

MICRO-MATERIAL HANDLING, EMPLOYING E-BEAM COATINGS OF COPPER AND SILVER

S. Matope^{1*}, A.F.van der Merwe² & Y.I.Rabinovich³

^{1,2} Department of Industrial Engineering
Stellenbosch University, South Africa
¹ smatope@sun.ac.za; ² andrevdm@sun.ac.za

³Particulate Department
Florida University, United States of America
yrabinovich@perc.ufl.edu

ABSTRACT

Van der Waals forces and other adhesive forces impose great challenges on micro-material handling. Mechanical grippers fail to release micro-parts reliably because of them. This paper explores how the problematic Van der Waals forces may be used for micro-material handling purposes using surface roughnesses generated by e-beam coatings of copper and silver on silicon. An atomic force microscope, model Asylum MFP 3 D-Bio with version 6.22A software, was used to measure the forces exerted by the surfaces. A silver coating of 1.41 nm *rms* surface roughness value is found to exert the highest Van der Waals force, followed by a copper coating of 2.72 nm *rms*; a copper coating of 217 nm *rms* exerts the least force. This implies that, in a reliable micro-material handling system, these coatings are suitable for the interactive surfaces of the placement position, micro-gripper, and the pick-up position respectively.

OPSOMMING

Van der Waalskragte en ander bindingskragte hou steeds groot uitdagings in vir mikro-materiaalhantering. As gevolg van hierdie bindingskragte stel meganiese gryptoerusting nie die mikro-partikels vry nie. Hierdie artikel ondersoek hoe die Van der Waalskragte gebruik kan word vir die mikro-materiaalhanteringsproses deur die gebruik van oppervlakgrofheid gegenereer deur 'n e-straal-laagbedekking van koper en silwer op silikon. 'n Atoomkrag mikroskoop, model Asylum MFP 3 D-Bio met weergawe 6.22A programmatuur, is gebruik om die kragte deur die oppervlakke uitgeoefen te meet. Daar is gevind dat 'n silwer laagbedekking met 'n oppervlakgrofheid van 1.41nm wortel-gemiddelde-kwadraat (wgk) die hoogste Van der Waalskrag uitoefen, gevolg deur 'n koper laagbedekking met 'n oppervlakgrofheid van 2.72nm wgk; 'n koper laagbedekking met 'n grofheid van 217nm wgk het die kleinste krag uitgeoefen. Dit impliseer dat, vir 'n betroubare mikro-materiaalhantering-sisteem, hierdie laagbedekkings geskik is vir die interaktiewe oppervlakke van die plasingsposisie, die mikro-gryper en die optelposisie.

¹ The author was enrolled for a PhD (Manufacturing Engineering) degree in the Department of Industrial Engineering, Stellenbosch University.

* Corresponding author

1. INTRODUCTION

As work parts are down-scaled to micro-parts, adhesive forces gain the upper hand in their manipulation. These adhesive forces include Van der Waals forces, surface tension forces, and electrostatic forces. Gravity release is hampered because the gravitational force is less significant than the other forces [5, 4, 2]; micro-parts would continue sticking to the micro-gripper. Vibrations may be used to release the micro-part, but precision placement would not be possible [2]. This paper explores the picking and placing of micro-parts employing one of the adhesive forces (Van der Waals force) using electron beam (e-beam) evaporation coatings of copper and silver. The e-beam depositions generate a surface roughness of a specific root mean square (*rms*) value that greatly influences the Van der Waals forces exerted [7, 12, 3]. This paper, with experimental data, is a follow-up of an earlier publication in which the application of Van der Waals forces in micro-material handling operations was modelled [9]. In the modelling (which employed the formula of Rabinovich *et al.* [11]), it was observed that for a reliable picking of a micro-part in a micro-material handling system, the picking place should exert less Van der Waals force than the micro-gripper; and the gripper, in turn, should exert less force than the placement position for an effective release. It was observed that the rougher the surface, the lower the Van der Waals force exerted. The experimental evidence shown in this paper proves these notions.

2. THEORETICAL FORMULAE

The value of the non-retarding Van der Waals force (also referred to as a dispersion force) between an ideally smooth sphere and a flat sample can be calculated using Equation 1 [10, 1].

$$F = AR/6H^2 \quad (1)$$

where A is the Hamaker coefficient (a material property that determines the intensity of the Van der Waals force exerted by a given substance), R is the radius of the sphere, and H is the separation distance between the interacting surfaces. In practice, when the surfaces are in contact, the distance H can be taken as $H_0 = 0.3$ nm, since surface roughness would prevent total contact.

An approximate Hamaker coefficient between dissimilar materials, 1 and 2, is given by Equation 2 [6]:

$$A_{12} = (A_{11} A_{22})^{0.5} \quad (2)$$

For the rough flat sample, the dispersion adhesion force can be calculated employing Equation 3, which incorporates a correction factor of $+1.48$ rms [11, 8].

$$F_{ad} = \frac{AR}{6H_0^2} \left[\frac{1}{(1 + R/1.48rms)} + \frac{1}{(1 + 1.48rms/H_0)^2} \right] \quad (3)$$

The same correction factor of separation distance ($+1.48$ rms) is applied to Equation 1 in order to obtain a formula for non-contact dispersion force between a rough plane and smooth sphere, resulting in Equation 4. This equation is used to identify whether Van der Waals forces are the only ones existing in a given experimental case [11].

$$F = AR/6(H + 1.48rms)^2 \quad (4)$$

Derivative of Equation 1 (force for smooth samples) is

$$dF/dH = AR/3H^3 \quad (5)$$

When a probe of the atomic force microscope (AFM) is brought into close proximity with an interactive surface, it experiences an attractive force and jumps into contact with the surface after reaching a certain threshold-separation distance. For the ‘jump-in’ distance, H_j , the force derivative is equal to the spring constant of the cantilever as represented by Equation 6:

$$dF / dH(H = H_j) = k \tag{6}$$

Therefore, the theoretical ‘jump-in’ distance for smooth samples can be calculated using Equation 7 (a combination of Equations 5 and 6):

$$H_j = \sqrt[3]{AR/(3k)} \tag{7}$$

3. DESCRIPTIONS OF EXPERIMENTS ON E-BEAM DEPOSITED MATERIALS

An atomic force microscope (AFM), model Asylum MFP 3 D-Bio with version 6.22A software, was used to measure the actual Van der Waals forces exerted by the e-beam deposited samples. The aim of the experiment was to obtain practical evidence to validate the Van der Waals forces modelled in Matope *et al.* [9] concerning their applicability to micro-materials.

The experimental conditions were as follows:

- Temperature: 23°C
- Atmospheric pressure: 101.325 kPa
- Humidity level: 20%

The experiments were conducted using an AFM cantilever with a smooth, spherical, silica tip of 2.5 μm radius, and an *rms* surface roughness value of 0.2 nm. The velocity of approach and retract of the AFM silica sphere (which was attached to the AFM’s cantilever) was 2 μm/s. The arrangement is shown in Figure 1.

Experiments were conducted on three samples: two of copper (Cu) and one of silver (Ag). These were Cu 5, Cu 20, and Ag 20 (where the numeric values refer to the e-beam deposition times in minutes - for example, Cu 5 stands for copper deposited for five minutes). Figure 2 shows the topography of an e-beam deposited layer as observed by an AFM. The generation of the e-beam coatings is detailed by Matope *et al.* [9].

Three different cantilevers were used: two with the same $k = 0.27$ N/m (for copper specimens), and the third with $k = 0.17$ N/m (for the silver specimen). (A different type was used for the silver specimen because the first two cantilevers were broken and there were no more of the same type.) The Hamaker coefficient for the interaction between silica and copper was taken as $A = 7.7 \times 10^{-20}$ J; and for silica and silver as $A = 1.5 \times 10^{-19}$ J.

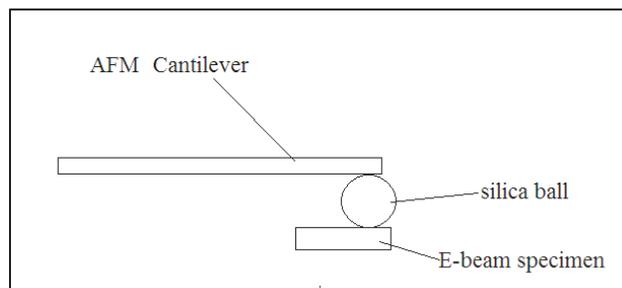


Figure 1: Arrangement of the AFM cantilever and e-beam specimen

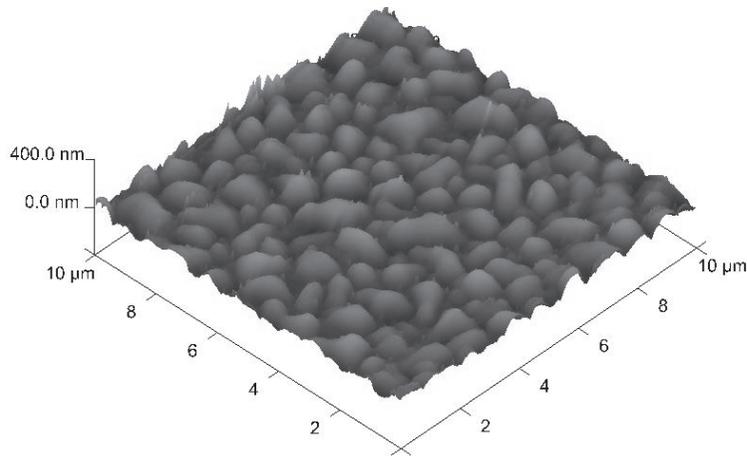


Figure 2: Atomic force micrograph of copper [9]

Approaching curves (also referred to as extending curves) and retracting curves were plotted depicting the variation of the Van der Waals forces, F , with respect to separation distance, H . Extending curves enable identification and evaluation of active non-contact forces (Van der Waals, magnetic, electrostatic, and others) in a given case. Retracting curves indicate the amount of detachment (adhesion) force.

4. EXPERIMENTAL RESULTS

4.1 Extending curves

Figures 3 to 5 are extending curves for samples Cu 5, Cu 20, and Ag 20 respectively. In each of the Figures, the curves labelled 1 are the experimentally-obtained graphs; curves labelled 2 are the theoretic non-retarding dispersion force for smooth samples (given by Equation 1); and curves labelled 3 represent the theoretic force for rough samples (given by Equation 4). H is the experimental distance between the silica sphere and peaks of the e-beam coatings. The dashed line shows the sample's 'jump-in' region in which the silica sphere is attracted to the e-beam layer. Point 'A' corresponds to the force derivative as given by Equation 6.

For all samples, the experimental force (indicated by curve 1) agrees with the theory of the dispersion force (curve 2) obtained using Equation 1. Correction of distance H (between peaks of a rough surface and a smooth sphere) made in Equation 4 improves agreement between the theory and the experiment. However, for the very rough sample Cu 20, the correction factor for congruence between experiment and theory should be about 10 nm rather than that suggested by Equation 4, 1.48 *rms*.

Besides the values of the non-contact attractive force versus the separation distance, the information about the force derivative can be obtained from the 'jump-in' points 'A' in Figures 2 to 4. These results are given in Table 1.

Table 1: The theoretical (Equation 7) and experimental 'jump-in' distances, H_j

Sample	$k = dF/DH (H=H_j)$, N/m	H_j theoretical, nm (Equation 7)	H_j experimental, nm
Cu 5	0.27	6.3	8.3
Cu 20	0.27	6.3	6.2
Ag 20	0.17	9.2	12.2

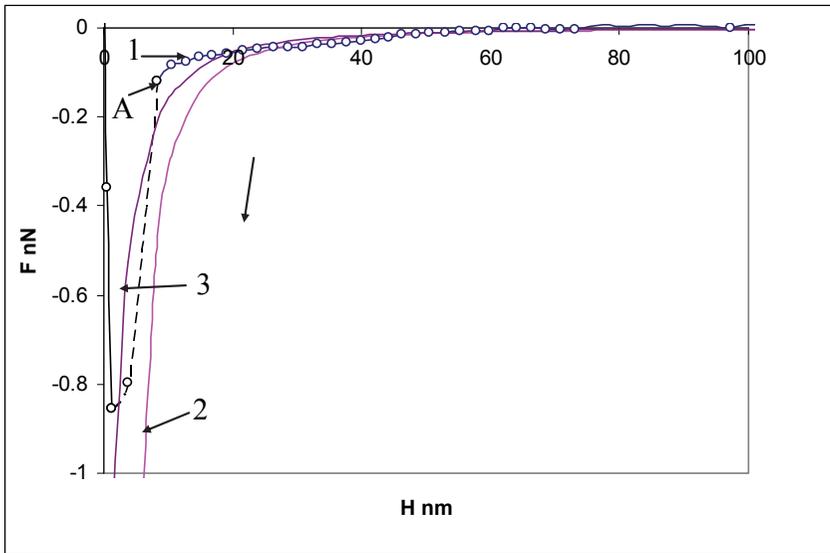


Figure 3: Copper (Cu 5) extending curves

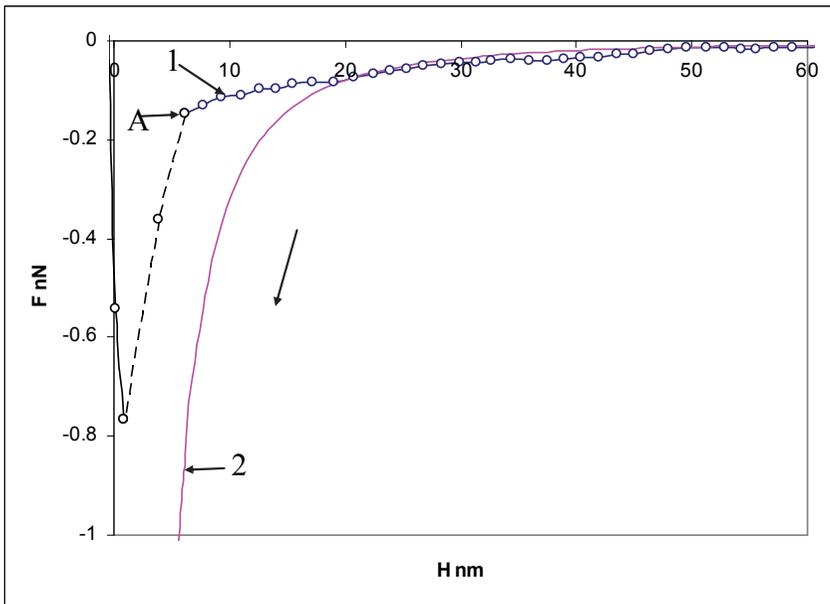


Figure 4: Copper (Cu 20) extending curves

The 'jump-in' regions and the position of point 'A' are very minimal in the nano-range and in the non-retarded region. This proves that Van der Waals forces are the predominant forces in this case, not electrostatic or magnetic forces, nor surface tension forces. Had these last three forces been dominant, the 'jump-in' region would have extended into the micro-range.

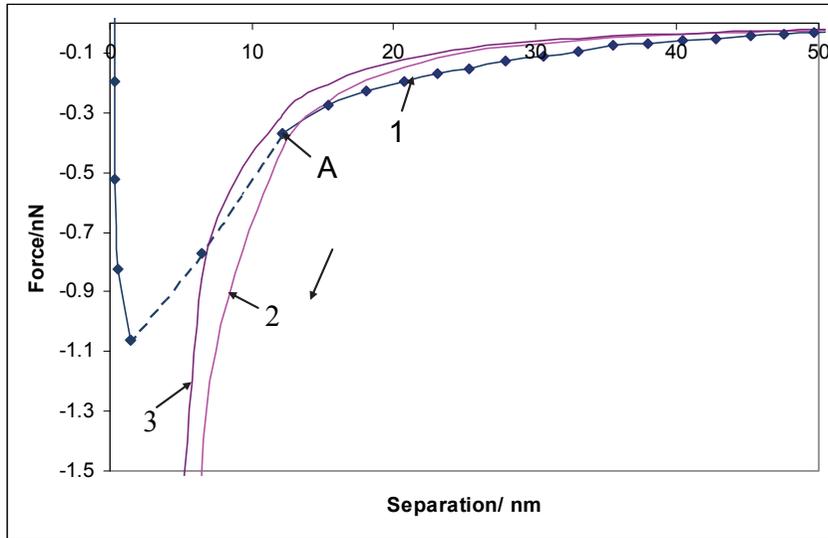


Figure 5: Silver (Ag 20) extending curves

4.2 Retracting curves

Figures 6 to 8 show retracting curves for Cu 5 (Figure 6), Cu 20 (Figure 7), and Ag 20 (Figure 8). The chosen curves demonstrate the value of the adhesion (detaching) force that is close to the average value of the overall force measurements of a given case. Average Van der Waals forces and the scattering of forces are given in Table 2.

Table 2: Average results of adhesion force and Van der Waals force, obtained from retracting curves

Sample	Surface roughness <i>rms</i> , nm	Experimental average adhesion force, nN
Cu 5	2.72	24±12
Cu 20	217	17±10
Ag 20	1.41	111±15

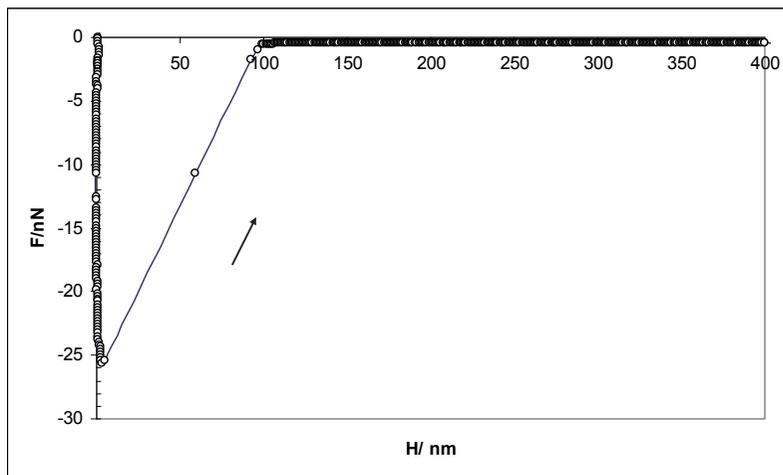


Figure 6: Retracting curve for Cu 5

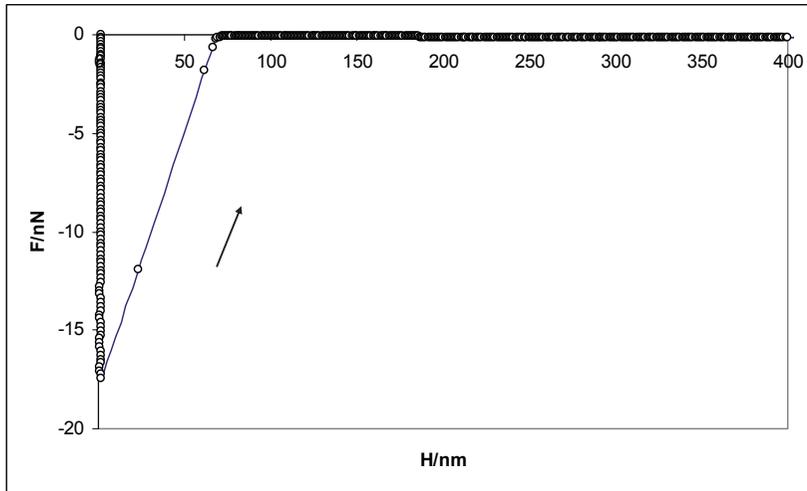


Figure 7: Retracting curve for Cu 20

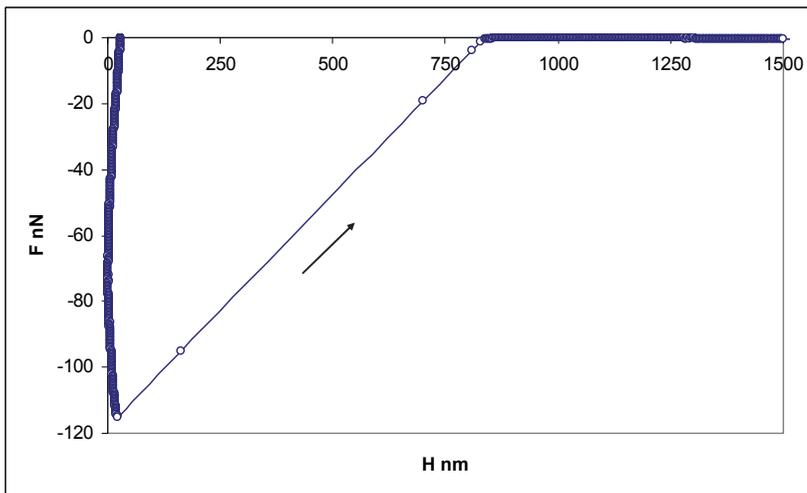


Figure 8: Retracting curve for Ag 20

These results are summarised graphically in Figure 9: Ag 20 exerts the largest force, followed by Cu 5; Cu 20 exerts the least force.

The experimental results prove that the rougher the e-beam coating, the less the Van der Waals forces exerted. Cu 20 is the roughest and exerts the least force, while Ag 20 is the smoothest and exerts the greatest force. A reliable micro-material handling system requires that the place from which a micro-part is picked exerts the smallest force, and the releasing place should exert the largest. Therefore Cu 20 is suitable for the picking place, Cu 5 for the micro-gripper's interactive surface, and Ag 20 for the placement position.

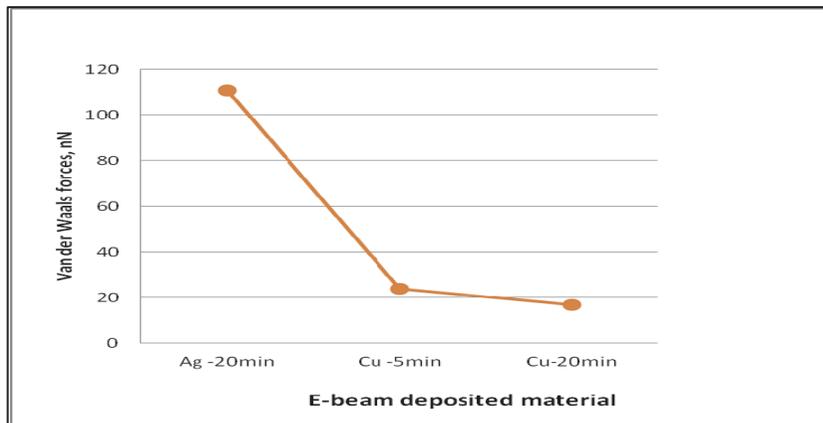


Figure 9: Experimental Van der Waals forces exerted by e-beam deposited surfaces of silver (Ag) and copper (Cu)

5. CONCLUSION

It was conclusively observed that e-beam coatings generated over different deposition periods result in topographies of different *rms* values of surface roughness that exert different Van der Waals forces. The experiments proved that the rougher the coating, the less the exerted Van der Waals forces, as modelled by Matope *et al.* [9]. The copper coating deposited for 20 minutes (Cu 20) had an *rms* surface roughness value of 217 nm, and it exerted an average Van der Waals force of 17 nN; Cu 5 of *rms* value of 2.72 nm exerted 24 nN; and silver deposited for 20 minutes (Ag 20) exerted the largest force of 111 nN because of its *rms* value of 1.41 nm. Therefore, in a reliable micro-material handling system, and given these three samples, Cu 20 would be suitable for the picking position, Cu 5 for the micro-gripper's interactive surface, and Ag 20 for the placement position.

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